Limitations of Lower-Bound Methods for the Wire Complexity of Boolean Operators

Andrew Drucker
EECS Dept. and CSAIL
MIT
Cambridge, MA 02139
adrucker@mit.edu

Abstract—We study the circuit complexity of Boolean operators, i.e., collections of Boolean functions defined over a common input. Our focus is the well-studied model in which arbitrary Boolean functions are allowed as gates, and in which a circuit’s complexity is measured by its depth and number of wires. We show sharp limitations of several existing lower-bound methods for this model.

First, we study an information-theoretic lower-bound method due to Cherukhin, that yields bounds of form \( \Omega(n \cdot \lambda_{d-1}(n)) \) on the number of wires needed to compute cyclic convolutions in depth \( d \geq 2 \). This was the first improvement over the lower bounds provided by the well-known super-concentrator technique (for \( d = 2.3 \) and for even \( d \geq 4 \)). Cherukhin’s method was formalized by Jukna as a general lower-bound criterion for Boolean operators, the “Strong Multiscale Entropy” (SME) property. It seemed plausible that this property could imply significantly better lower bounds by an improved analysis. However, we show that this is not the case, by exhibiting an explicit operator with the SME property that is computable in depth \( d \) with \( \mathcal{O}(n \cdot \lambda_{d-1}(n)) \) wires, for \( d = 2.3 \) and for even \( d \geq 6 \).

Next, we show limitations of two simpler lower-bound criteria given by Jukna: the “entropy method” for general operators, and the “pairwise-distance method” for linear operators. We show that neither method gives super-linear lower bounds for depth 3. In the process, we obtain the first known polynomial separation between the depth-2 and depth-3 wire complexities for an explicit operator. We also continue the study (initiated by Jukna) of the complexity of “representing” a linear operator by bounded-depth circuits, a weaker notion than computing the operator.

Keywords—bounded-depth circuits; circuit lower bounds; arbitrary gates

I. INTRODUCTION

A. Circuits with arbitrary gates

This paper continues the study of the circuit complexity of Boolean operators, that is, functions \( F : \{0, 1\}^n \rightarrow \{0, 1\}^m \). For ease of discussion, we will focus on the common setting \( m = n \). Typically we regard \( F = (f_1, \ldots, f_n) \) as a collection of \( n \) Boolean functions. By comparing the circuit complexity of \( F \) to the individual complexities of the \( f_i \)'s, we are asking: how much easier is it to compute the \( f_i \)'s together than to compute them separately?

A great deal of work, e.g., in [22], [23], [8], [4], [5], [18], [17], [20], [6], [10], [11], [13], has studied the circuit model in which unbounded fanin is allowed, and in which circuit gates can apply arbitrary Boolean functions to their inputs. In this model, we study the number of wires required in such a circuit to compute \( F \), a quantity we denote as \( s(F) \).

While allowing gates to compute arbitrary Boolean functions is physically unrealistic, there are a number of motivations to study this model. First, it arguably provides a natural measure of the “information complexity” of Boolean operators. Second, lower bounds in this strong circuit model are highly desirable, since they also apply to a variety of more realistic models. Third, several natural circuit lower-bound criteria apply even to circuits with arbitrary gates, and it seems worthwhile to understand how far techniques of this kind can carry us. Finally, for at least one important class of Boolean operators—the \( \mathbb{F}_2 \)-linear operators, naturally computable by \( \mathbb{F}_2 \)-linear circuits—it remains unclear whether allowing arbitrary gates in our circuits even confers additional power.

Any individual Boolean function can be trivially computed with \( n \) wires in the arbitrary-gates model, so \( n^2 \) wires always suffice to compute an operator \( F \). In general, this is not far from optimal: random (non-linear) operators require \( \Omega(n^2) \) wires to compute [13]. Thus random collections of Boolean functions are, in a sense, “computationally orthogonal” to one another. It would be extremely interesting to identify an explicit function collection with this property: however, proving a super-linear lower bound \( s(F) = \omega(n) \) for an explicit operator \( F \) is a long-standing open problem.

This has led researchers to consider circuits with arbitrary gates but restricted depth. Even depth-2 circuits in this model are powerful, and their study was strongly motivated by work of Valiant [23] (see [24]), who showed that any operator with depth-2 wire complexity \( \omega(n^2 \ln \ln n) \) also cannot be computed by linear-size, logarithmic-depth Boolean circuits (of fanin 2). However, the known lower bounds for depth 2 are too weak to apply Valiant’s results. For depth-2 circuits, the best bounds for explicit operators are of form \( \Omega(n^{3/2}) \) [6], [10]. For depths 3 and 4, the best bounds are \( \Omega(n \ln n) \) and \( \Omega(n \ln \ln n) \) respectively [6]: for higher constant depths the known bounds (described in Section I-B) are barely super-linear [8], [18], [6].

One might suspect that the difficulty of proving strong lower bounds stems from the unrealistic strength of the circuit model being studied. A seemingly much more modest
aim is to prove lower bounds in the linear circuit model over $F_2$. In this model, we require the circuit gates to compute $F_2$-linear functions; we again allow unbounded fanin. Given some linear operator $L : F_2^n \rightarrow F_2^n$, we let $s^0(L)$ denote the number of wires needed to compute $L$ with a linear circuit. Lupanov [15] (and later Bublitz [3]) showed that $s^0(L) = O(n^2/\ln n)$, and that this bound is tight if $L$ is chosen randomly.

Unfortunately, the known lower bounds for explicit linear operators in the linear circuit model are just as discouragingly weak as for operators in the arbitrary-gates model. Moreover, since the lower bounds quoted earlier were shown for non-linear operators, the situation is actually slightly worse in the linear case: for example, for depth-2 circuits, the best known lower bound for an explicit linear operator is $\Omega\left(n \left(\frac{\ln n}{\ln \ln n}\right)^2\right)$, proved very recently [9].

Thus, it is a major unmet challenge to develop lower-bound techniques that effectively exploit the specific behavior of linear circuits. In fact, it is an open question whether $s^0(L)$ can be noticeably larger than $s(L)$, that is, whether non-linear gates can ever help us compute linear operators more efficiently. However, we also cannot rule out the possibility that all linear operators $L$ are computable by depth-2, non-linear circuits of size $O(n \cdot \text{polylog}(n))$; see [13]. (We at least prove, in the full version, that $s(L) = \Omega(n \ln n)$ for random $L$.)

Since there are relatively few lower-bound methods for circuits with arbitrary gates, it is important to understand the power and limitations of existing methods. In this work we focus on three such methods.

**B. The Strong Multiscale Entropy Method**

The first method we study was developed by Cherukhin [6], and used to obtain the best known explicit lower bounds on bounded-depth wire complexity. The bounds apply to the cyclic convolution operator over $F_2^n$, and are of form $\Omega_d(n \cdot \lambda_{d-1}(n))$ for depth $d > 1$.\(^2\)

Here, $\lambda_d(n)$ is an unbounded function in $n$, which grows ever-more-slowly as $d$ increases; its growth is extremely slow even for modest values of $d$. We have\(^3\)

$$\lambda_1(n) = \Theta(\sqrt{n}), \quad \lambda_2(n) = \Theta(\ln n), \quad \lambda_3(n) = \Theta(\ln \ln n),$$

and for higher $d$, $\lambda_d(n) = \lambda_{d-2}(n)$. The precise definition is in Section III-B.

\(^1\)A lower-bound criterion specific to linear circuits, based on matrix rigidity, has been given by Valiant [23]. In principle this method is capable of showing strong lower bounds. However, except for some limited success in depth 2 [18], no one has proved sufficiently-strong rigidity lower bounds on explicit $F_2$-matrices to imply circuit lower bounds in this way. See [14] for a survey of this line of work.

\(^2\)Cherukhin proved his result for depths 2 and 3 earlier in [7]. The paper [6] contains a unified proof for all constant depths.

\(^3\)The $\lambda_d(\cdot)$ functions are defined differently in [18], [9]. We follow [20], [6], [12] instead, and we have converted the bounds quoted from other papers to match our convention.

The longstanding previous best lower bounds for explicit operators (including cyclic convolution) were of form $\Omega\left(\frac{n \cdot \ln n}{\ln \ln n}\right)$ for depth 2 [19] and $\Omega_d(\lambda_d(n))$ for $d \geq 3$ [8], [18], [2], and were based on the superconcentrator technique [22], [23]. For depths 2, 3 and for even depths $d \geq 4$, Cherukhin’s work gives asymptotic improvements on these older bounds; for odd depths $d \geq 5$, his bounds match the best previous ones from [18]. Cherukhin’s lower-bound method does not apply to linear operators. (For $d \geq 3$, the best known lower bounds for computing an explicit linear operator are of form $\Omega_d(n \cdot \lambda_{d-1}(n))$ [8, p. 215], [9]. These bounds, along with the $\Omega\left(\frac{n (\ln n)^3}{\ln \ln n}\right)$ bound for depth 2 from [9], are valid against circuits with arbitrary gates.\(^\star\)

Cherukhin’s method, developed specifically for the convolution operator, was later formulated by Jukna [12, Chap. 13] as a general property of operators that yields a lower bound of form $\Omega_d(n \cdot \lambda_{d-1}(n))$. This operator property is called the Strong Multiscale Entropy (SME) property. Very roughly speaking, the SME property states that there is a large “information flow” between many subsets of the input and output coordinates of an operator. The precise definition has two noteworthy aspects. First, the SME property requires for this information flow to be large when measured with respect to many different partitions of the input and output coordinates, at many different “scales” (i.e., varying the size of the input and output blocks). Second, the measure of information flow between an input and output block is defined with respect to a well-chosen set of restrictions of the original operator. The SME property will be defined in Section III-B.

The earlier superconcentrator technique works by showing (also using “information flow”-type arguments) that for certain operators $F$, any circuit to compute $F$ must have a strong connectivity property: it must be a so-called superconcentrator graph. This allows one to apply known lower bounds on the number of edges in bounded-depth superconcentrators (on $n$ input and output vertices). The power of this method is inherently limited, since for $d \geq 3$, the smallest depth-$d$ superconcentrators have $\Theta_d(n \cdot \lambda_n(n))$ edges [8], [18], [2]. Also, there exist superconcentrators with $O(n)$ wires [22], [23]; such graphs cannot have constant depth, but may have depth that grows extremely slowly in $n$ [8]. In contrast with the superconcentrator technique, the SME property has an inherently information-theoretic definition, and the associated lower bounds are proved by a combination of graph-theoretic techniques from earlier work [18], [20] with novel information-theoretic techniques. For constant-depth circuits, no limitations on the method were known prior to our work, and it seemed plausible that the SME property might imply significantly stronger lower
bounds by an improved analysis.\footnote{For larger depths, some limitations of the SME criterion follow from previous work. In particular, the cyclic convolution operator over $\mathbb{F}_2$, which satisfies the SME property, can be computed in depth polylog($n$) using $O(n \log n \log \log n)$ wires. To see this, we first note that cyclic convolution of length $n$ in $\mathbb{F}_2$ easily reduces to multiplying two polynomials in $\mathbb{F}_2[x]$, each of degree at most $2n-1$. For the latter task, we can use an algorithm of Schönhage [21] (see [16]).}

\section{Two simpler lower-bound methods}

We also study two other lower bound methods, both due to Jukna. These methods are simpler than the SME method, and have only been shown to imply lower bounds for depth 2. However, we feel they are still of interest due to their elegance, and due to the fact that the important depth-2 case is still not well-understood.

The first of these methods is the so-called “entropy method” of Jukna [10]. Like the SME method, this method is a complexity measure of Boolean operators whose definition is information-theoretic: the method identifies information that passes between certain subsets of inputs and outputs, and argues that there must be many wires to carry this information. (In fact, the property of operators used by Jukna’s entropy method can be viewed as a relaxation of the SME property, as will be apparent from the definitions.) Using this method, Jukna proved bounds of form $\Omega(n^{3/2})$ for the number of wires required in depth-2 circuits for multiplication of two $\sqrt{n}$-by-$\sqrt{n}$ matrices over $\mathbb{F}_2$. Like the SME method, Jukna’s entropy method does not yield superlinear lower bounds for computing linear operators.

The next lower-bound method we study, also due to Jukna [11] (building on work of Alon, Karchmer, and Wigderson [1]), does apply to linear operators, and indeed is specific to these operators. Jukna showed that if the columns of a matrix $A \in \mathbb{F}_2^{n \times n}$ have pairwise Hamming distance $\Omega(n)$, then any depth-2 circuit (with arbitrary gates) computing the linear transformation $x \rightarrow Ax$ must have $\Omega(\sqrt{n} \log n)$ wires [11]. This lower-bound criterion applies to a wide range of transformations, including random ones. We will refer to this technique as the “method of pairwise distances.”

Jukna’s result is actually stronger: the $\Omega(\frac{n \log n}{\log \log n})$ lower bound applies to any depth-2 circuit that merely computes $Ax$ correctly when $x$ is a standard basis vector $e_i$. Such a circuit is said to “represent” the transformation $Ax$ (relative to the standard basis)—a weaker notion than computing the transformation, if we allow non-linear gates. It seems worthwhile to understand how much of the difficulty of computing a linear transformation is “already present” in the simpler task of representing it relative to some basis. In our work, we are broadly interested in the complexity of representing linear transformations relative to various bases; we regard the method of pairwise distances as one particular lower-bound technique within this framework.

\section{Our results}

\subsection{Limitations of entropy-based methods} As our most significant (and most technically involved) result, we show that Cherukhin’s lower-bound method, formalized by Jukna as the SME property, is inherently limited as a lower-bound criterion for the wire complexity; there is an explicit operator with the SME property that is computable with $O(n \cdot \lambda_{d-1}(n))$ wires, when $d = 2, 3$, or when $d \geq 6$ is even. For other $d > 1$, this gives an upper bound of $O(n \cdot \lambda_{d-2}(n))$ wires. Thus, the Cherukhin-Jukna analysis of the SME lower-bound criterion is essentially tight.

The operator we exhibit, called the “Dyadic Interval Replication” (DIR) operator, is fairly natural, and can be roughly described as follows. Let $n := 2^k$. The input is a string $x \in \{0, 1\}^n$, viewed as a labeling of the leaves of $T_k$, the complete binary tree of depth $k$, along with a specified subtree $T'$ of $T_k$. The desired output is the labeling $z \in \{0, 1\}^n$ in which the leaf labels of $T'$ in $x$ have been “copied” to all other subtrees of the same height. This operator is designed to create significant information flow between all parts of the input and output; the subtree $T'$ will be encoded in the input in a way that is chosen to help ensure the SME property.

Our efficient bounded-depth circuits for the DIR operator are built by an induction on the depth $d$. The basic idea is that, when the subtree $T'$ to be copied is small, we can “shrink” the input $x$, discarding most of the labelings outside of $T'$. We then either perform the replication task in a direct fashion, or, if the input has been shrunk substantially enough, we inductively apply our circuits for lower depths. By carefully optimizing the set of sizes to which we attempt to shrink the input, we obtain the upper bounds quoted above. This approach also shows that the DIR operator has linear-sized circuits of depth $d = \alpha(n) + 2$, where $\alpha(n) := \min\{d : \lambda_d(n) \leq 1\}$ is an extremely slowly-growing function. The idea of attacking a problem at different “scales,” and applying induction, has appeared earlier in efficient constructions of bounded-depth superconcentrators [8] and bounded-depth circuits to compute good error-correcting codes [9], although the details are different in each case.

We share with earlier authors the belief that, for the cyclic convolution operator, it should be possible to prove significantly better lower bounds for bounded depth—say, bounds of form $\Omega(n^{1+\varepsilon})$ for any constant $\varepsilon > 0$. Our work’s message is simply that such lower bounds will have to exploit more of the specific structure of this operator. It seems likely that this will require powerful new ideas. We do hope, however, that our DIR example may be a useful reference point for future work in this area.

The construction and analysis of the DIR operator occupy
the body of this extended abstract. We will only describe our other results, whose proofs are in the full version.

As our next contribution, we turn to study the limits of Jukna’s entropy method. We give a simple example of an operator from $2n$ input bits to $n$ output bits, which is computable by depth-3 circuits with $O(n)$ wires but requires $\Omega(n^{3/2})$ wires to compute in depth 2. The operator is a simplified variant of matrix multiplication over $\mathbb{F}_2$, in which one of the two matrices is required to contain exactly one 1-entry. The lower bound follows by the same analysis used in [10] to prove the same lower bound for ordinary matrix multiplication over $\mathbb{F}_2$. Our example shows that the entropy method as formalized in [10] does not provide a nontrivial lower-bound criterion for depth-3 circuits.

As super-linear lower bounds are already known for the depth-3 wire complexity of certain operators, our negative result on Jukna’s entropy method should be interpreted as a note of caution, rather than as a strong barrier to progress in circuit complexity. However, the operator we define to prove our result is also the first known example of a polynomial separation between depth-2 and depth-3 wire complexities—a finding of independent interest. (A polynomial separation between depth-2 and depth-3 is shown in [9], for the task of computing the encoding function of certain non-explicit linear codes.)

2) Results on linear transformations: In the rest of our work, we study the complexity of representing linear transformations over $\mathbb{F}_2^n$. While Lupanov [15] showed that random linear transformations require $\Omega(n^2/\ln n)$ wires to compute by linear circuits, Jukna [11] showed that, if we allow non-linear gates, $O(n\ln n)$ wires suffice to represent any linear transformation. (He showed this for the standard basis, but his method extends easily to all other bases.) We show that, relative to any fixed basis $B$, most linear transformations require $\Omega(n\ln n)$ wires to represent relative to $B$. Our result shows that Jukna’s upper bound is in general optimal. For our proof, we use a simple trick (similar to a technique in [13]) to reduce arbitrary circuits to a special, restricted class; we then apply a standard counting argument.

Recall that Jukna’s method of pairwise distances [11] implies a lower bound of $\Omega(\binom{n}{\ln n})$ on the number of wires needed to represent a large class of linear transformations by depth-2 circuits. Jukna asked whether the “annoying” $(\ln \ln n)^{-1}$ factor in his result could be removed, to match the upper bound he proved for arbitrary matrices. We show that in fact it cannot: there is a matrix family $\{A_n \in \mathbb{F}_2^{n \times n}\}$ whose columns have pairwise distance $\Omega(n)$, for which we can compute the transformation $x \rightarrow A_n x$ using a depth-$2, \mathbb{F}_2$-linear circuit with $O(\binom{n}{\ln \ln n})$ wires. Our construction involves an application of combinatorial designs defined by polynomials over finite fields.

We also show that, for depth-3 circuits, the pairwise-distance method fails completely: there is a matrix family $\{A_n \in \mathbb{F}_2^{n \times n}\}$, whose columns have pairwise distance $\Omega(n)$, and for which we can compute $x \rightarrow A_n x$ using a depth-$3$ linear circuit with $O(n)$ wires. Recently, Gál et al. [9] proved a related result: there is a linear error-correcting code $L : \{0,1\}^{\Omega(n)} \rightarrow \{0,1\}^n$ with minimum distance $\Omega(n)$, whose encoding function is computable by depth-3 linear circuits with $O(n\ln \ln n)$ wires. They also show this is optimal for any such code, even if arbitrary gates are allowed. In fact, they determine fairly precisely the minimal wire complexity of computing a good error-correcting code for all depths $d \geq 2$: for depth $2$, the answer is $\Theta\left(n \left(\frac{\ln n}{\ln \ln n}\right)^2\right)$, and for depth $d \geq 3$, the answer is $\Theta_d(n \cdot \lambda_d(n))$. As a corollary, this implies that the pairwise-distance method cannot give bounds better than $\Omega(n\ln \ln n)$ for depth $3$; our result sharpens this by removing the $(\ln \ln n)$ factor. Comparing our work with [9] also shows that, while the generator matrices of good linear codes do have columns with high pairwise distance, the property of being a good code is an inherently stronger lower-bound criterion than the pairwise-distance method.

Finally, we identify another potential pitfall of circuit-size lower bounds based on hardness of representing linear transformations. We show that for invertible linear transformations $L$, there is always a basis $B$ and a depth-$3$ circuit $C$ of size $O(n)$ such that $C$ represents $L$ relative to $B$. (Non-linear gates are provably necessary in this construction.) Thus in attempts to prove new circuit lower bounds for depths greater than 2, we must at least take care in choosing which basis we use to analyze our linear transformation.

II. Preliminaries

We use $e_1, \ldots, e_n$ to denote the standard basis vectors in $\mathbb{F}_2^n$. We use $||g||$ to denote the Hamming weight of $g \in \{0,1\}^n$. Given a gate $g$ in a circuit $C$, the depth of $g$ is defined as the maximal number of edges (i.e., wires) in any directed path from an input gate to $g$, where each step in the path follows a wire in $C$ in its direction of information flow. The depth of $C$ is the maximum depth of any of its gates. When we construct circuits, we will refer to the depth-$d$ gates as being at “Level $d$.” Generally these circuits will not be layered; that is, wires may pass from Level $d$ to any Level $d' > d$.

A. Wire complexity of operators

A (total) operator (or mapping) is any function $F : \{0,1\}^n \rightarrow \{0,1\}^m$. Define $s(F)$ as the minimum number of wires in any circuit (using arbitrary Boolean functions at gates) which computes $F$. For $d \geq 0$, define $s_d(F)$ as the minimum number of wires in any circuit which computes $F$ and has depth at most $d$.

The following easy lemma, proved in the full version, allows us to “hash,” or compress, a standard basis vector down to fewer bits in a wire-efficient way.

**Lemma 1.** There is a $\mathbb{F}_2$-linear operator $H : \mathbb{F}_2^n \rightarrow \mathbb{F}_2^{|\sqrt{n}|}$, computable by a depth-$1$ circuit with $2n$ wires,
and such that for any two distinct standard basis vectors \( e_i, e_j \in \mathbb{F}_2^n \), the image vectors \( H(e_i), H(e_j) \) are distinct and each of Hamming weight 2.

III. Entropy and Circuit Lower Bounds

A. Entropy of operators

Given an operator \( F = (f_1, \ldots, f_m) : \{0,1\}^n \rightarrow \{0,1\}^m \), define the entropy

\[
\text{Ent}(F) := \log_2(|\text{range}(F)|)
\]
as the logarithm of the number of distinct outputs of \( F \). We have two easy facts, both from [10]:

**Fact 2.** Suppose we fix some assignment to a subset \( I \subseteq [n] \) of the inputs to \( F \), and let \( F' : \{0,1\}^{n-|I|} \rightarrow \{0,1\}^m \) be the resulting operator. Then \( \text{Ent}(F') \leq \text{Ent}(F) \).

**Fact 3.** Suppose that there is a subset \( S \subseteq [n] \), such that from the value \( F(x) \) one can always infer the values of all input bits \( x_i \) with \( i \in S \). Then, \( \text{Ent}(F) \geq |S| \).

Say we are given an \( x \in \{0,1\}^n \), a nonempty set \( I \subseteq [n] \), and an \( i \in I \). Let \( x[I,i] \) denote the vector obtained from \( x \) by setting the \( i \)th bit to 1, setting the \((i')\)th bit to 0 for each \( i' \in I \setminus \{i\} \), and leaving all other bits unchanged.

Letting \( F(x) \) be as above, and fixing some output coordinate \( j \in [m] \), define the function

\[
f_{I,i,j}(x) := f_j(x[I,i]).
\]

Now for \( J \subseteq [m] \), define a mapping \( F_{I,J} : \{0,1\}^{n-|I|} \rightarrow \{0,1\}^{|J|} \) by

\[
F_{I,J} := (f_{j,i,j})_{i \in I, j \in J}.
\]

Note, \( F_{I,J} \) has as its domain the bits \( \{x_\ell : \ell \not\in I\} \). (We will still write \( F_{I,J} = F_{I,J}(x) \), however.) We can now state Jukna’s entropy-based lower-bound criterion:

**Theorem 4.** [10] Let \( F : \{0,1\}^n \rightarrow \{0,1\}^m \). Let \( I_1, \ldots, I_p \) be a partition of \([n]\), and let \( J_1, \ldots, J_p \) be a partition of \([m]\) with the same number of parts. Then,

\[
s_2(F) \geq \sum_{i=1}^p \text{Ent}(F_{I_i,J_i}).
\]

B. Strong Multiscale Entropy

Next we define the Strong Multiscale Entropy property, which is a generalization due to Jukna [12, Chap. 13] of a lower-bound method of Cherukhin [6].

For a pair of integers \( N, m \geq n_0 \), we consider pairs \((\mathcal{I}, \mathcal{J})\) where \( \mathcal{I} \) is a collection of subsets of \([N]\) and \( \mathcal{J} \) is a collection of subsets of \([m]\). For an integer \( p \leq n_0 \), we say that \((\mathcal{I}, \mathcal{J})\) form an \( n_0 \)-partition at scale \( p \) if:

1. \( \mathcal{I} \) consists of \( p \) disjoint sets \( I_i \subseteq [N] \), with \( |I_i| = \lfloor n_0/p \rfloor \);
2. \( \mathcal{J} \) consists of \( \lfloor n_0/p \rfloor \) disjoint sets \( J_{i'} \subseteq [m] \), with \( |J_{i'}| = p \).

Say that a family \( \{F_N : \{0,1\}^N \rightarrow \{0,1\}^m\}_{N \geq 0} \) has the Strong Multiscale Entropy (SME) property, if there exists a parameter \( n_0 = n_0(N) = \Omega(N) \) along with constants \( C, \gamma > 0 \) such that, for every \( N \) and every \( p \in [C \sqrt{n_0}, n_0] \), there exists a pair \((\mathcal{I}, \mathcal{J})\) that form an \( n_0 \)-partition at scale \( p \), satisfying

\[
\text{Ent}(F_{I_i,J_{i'}}) \geq \gamma \cdot n_0, \quad \forall I_i \in \mathcal{I}, J_{i'} \in \mathcal{J}.
\]

We also define the enhanced SME property similarly to the above, except that we ask for a pair \((\mathcal{I}, \mathcal{J})\) satisfying Eq. (1) for all \( p \in [C, n_0] \).

To state the lower bounds for operators with the SME property, we need some definitions. We let \( g^{(i)} \) denote the \( i \)-fold composition of a function \( g : \mathbb{Z} \rightarrow \mathbb{Z} \). Suppose \( g \) satisfies \( 1 \leq g(n) < n \) for all \( n > 1 \); we then define \( g^* = \{1,2,3,\ldots\} \rightarrow \{0,1,2,\ldots\} \)

\[
g^*(n) := \min \{i : g^{(i)}(n) \leq 1\}.
\]

Following conventions in [20], [6], define a family of slowly-growing functions \( \lambda_d(n) \) as follows: let

\[
\lambda_1(n) := \lfloor \sqrt{n} \rfloor, \quad \lambda_2(n) := \lfloor \log_2 n \rfloor,
\]

and for \( d > 2 \), let

\[
\lambda_d(n) := \lambda_{d-2}(n).
\]

(\text{Note that } \lambda_3(n) = \Theta(\ln \ln n)).

Applying the technique of Cherukhin [6], Jukna proved:

**Theorem 5.** [12, Chap. 13] Suppose the operator family \( \{F_N : \{0,1\}^N \rightarrow \{0,1\}^m\} \) has the Strong Multiscale Entropy property. Then for any constant \( d \geq 2 \), any depth-\( d \) circuit to compute \( F_N \) has \( \Omega_d(N \cdot \lambda_{d-1}(N)) \) wires.

IV. Limitations of the SME Lower-bound Criterion

In this section we introduce an explicit Boolean operator called the “Dyadic Interval Replication” (DIR) operator, and use it to show that the Strong Multiscale Entropy property does not imply wire complexity lower bounds substantially better than those given by Theorem 5. We prove:

**Theorem 6.** There is an operator family \( \{D_{IR_N} : \{0,1\}^N \rightarrow \{0,1\}^{\lfloor n/N \rfloor}\} \), with the enhanced Strong Multiscale Entropy property, for which we have:

\[
s_2(DR_N) = \Theta(N^{3/2}) = \Theta(N \cdot \lambda_1(n));
\]

\[
s_3(DR_N) = \Theta(N \ln N) = \Theta(N \cdot \lambda_2(n));
\]

\[
s_5(DR_N) = \Theta(N \ln \ln N) = \Theta(N \cdot \lambda_3(n));
\]

For even \( d = d(N) \geq 6 \),

\[
s_d(DR_N) = \Theta(N \cdot \lambda_{d-2}(N)) = \Theta(N \cdot \lambda_{d-1}(N)),
\]

and so for constant, even values \( d \geq 6 \),

\[
s_d(DR_N) = \Theta_d(N \cdot \lambda_{d-1}(N)).
\]
For odd values \( d = d(N) \geq 7 \), we have

\[
 s_d(DIR_N) \leq s_{d-1}(DIR_N) = O(N \cdot \lambda_{d-2}(N)).
\]

The lower bounds come from Theorem 5. In the statements above, we are using the fact that \( \lambda_d(N) = \Theta(\lambda_{d+1}(N)) \) for even values \( d = d(N) \geq 4 \). We emphasize that our upper bounds for the specific operator DIR_N are also upper limits on the lower bounds that follow in general from the SME property.

The hidden constants in the \( O(\cdot) \) notation above are independent of \( d \). Thus, DIR_N is computable by a circuit with \( O(N) \) wires, of depth \( \alpha(N) + 2 \), where \( \alpha(N) := \min\{d : \lambda_d(N) \leq 1\} \) is an extremely slowly-growing function. On the other hand, the lower bounds from Theorem 5 hide a multiplicative constant that goes to \( 0 \) as \( d \to \infty \). So there may be room for some further tightening of the upper or lower bounds for all values of \( d \).

In Theorem 6, we show that DIR_N satisfies not only the SME property, but also the enhanced SME property. We do so to clarify that even this stronger property does not yield significantly better lower bounds than those given by Theorem 5.

A. The DIR operator

Now we define DIR_N and show it has the SME property. In our work in this section, it will be convenient to index vectors in \( \{0, 1\}^n \) as \( x = (x_0, \ldots, x_{n-1}) \), and regard the indices as lying in \( \mathbb{Z}_n \). For \( a \in \mathbb{Z}_n \), define

\[
 \text{shift}(x; a) := (x_a, x_1-a, \ldots, x_{(n-1)-a}),
\]

with index arithmetic over \( \mathbb{Z}_n \). We also use set addition: for \( A, B \subseteq \mathbb{Z}_n \), define \( A + B := \{a + b : a \in A, b \in B\} \) (with addition over \( \mathbb{Z}_n \)). For \( i \in \mathbb{Z}_n \), we write \( A + i := A + \{i\} \).

We consider input lengths \( N = 2 \cdot 2^k + \lceil \log_2 k \rceil \), for \( k \geq 1 \). We let \( n := 2^k \), and we regard inputs of length \( N \) to have the form

\[
 (x, y, r) \in \{0, 1\}^{n+n+\lceil \log_2 k \rceil}.
\]

We will consider \( r \) as an integer in \( [0, k - 1] \).\(^6\) Define the Dyadic Interval Replication operator DIR_N(\( x, y, r \) : \( \{0, 1\}^N \to \{0, 1\}^n \) by the following rule:

1) If the Hamming weight \( ||y|| \) is \( \neq 1 \), output \( z := 0^n \).

2) Otherwise, let \( i = i(y) \in \mathbb{Z}_n \) be the unique index for which \( y_i = 1 \). Output the string \( z \) given by

\[
 z_j := \text{shift}(x; i \cdot 2^r)(j \mod 2^r). \quad (2)
\]

Let us explain this definition in words. The input vector \( x \) divides naturally into \( n/2^r = 2^{k-r} \) substrings of length \( 2^r \). The operator DIR_N chooses one of these substrings, and outputs \( 2^{k-r} \) consecutive copies of this substring.

We can extend the definition to input lengths \( N \geq 6 \) not of the above form, by considering the input to be padded with irrelevant bits.

B. Establishing the SME property for DIR

**Lemma 7.** The family \{DIR_N\} has the enhanced SME property.

**Proof of Lemma 7:** The number of irrelevant bits in the input to DIR_N is not more than twice the number of relevant bits, so for the purposes of our asymptotic analysis, we may assume that \( N \) is of form \( N = 2 \cdot 2^k + \lceil \log_2 k \rceil \) with \( k \geq 1 \). Let \( n := 2^k \), and let \( n_0 := n = \Omega(N) \).

Let \( p \in [4, n] \) be given. Define collections \( I, J \) as follows. For \( t \in [p] \), let

\[
 I_t := \{0, 1, \ldots, [n/p]\} + (t - 1)[n/p]
\]

be the \( t^{th} \) consecutive interval of length \([n/p]\) in \( \mathbb{Z}_n \). For \( t' \in [[n/p]] \), let

\[
 J_{t'} := \{0, 1, \ldots, p\} + (t' - 1)p
\]

be the \((t')^{th}\) interval of length \( p \) in \( \mathbb{Z}_n \). Note that \((I, J)\) form an \( n_0 \)-partition at scale \( p \) for the input and output lengths of DIR_N.

Say we are given any \( t \in [p] \) and \( t' \in [[n/p]] \); we will show that \( \text{Ent}(\text{DIR}_{I_t, J_{t'}}) = \Omega(n) = \Omega(N) \). First, suppose that \( p \in [2^\ell, 2^{\ell+1}) \), where \( \ell > 0 \). Then, \( J_{t'} \) contains an interval \( J \) of form

\[
 \hat{J} = \{0, \ldots, 2^\ell - 1\} + s \cdot 2^{\ell - 1},
\]

for some \( s \in [0, 2^{\ell - 1}) \). We now fix assignments \((y^*, r^*)\) to part of the input to DIR_{I_t, J_{t'}}:

\[
 y^* := 0^n, \quad r^* := \ell - 1.
\]

Define DIR_{I_t, J_{t'}}(x) := DIR_{I_t, J_{t'}}(x, y^*, r^*). Using Fact 2 applied to DIR_{I_t, J_{t'}} , we have \( \text{Ent}(\text{DIR}_{I_t, J_{t'}}) \geq \Omega(\text{Ent}(\text{DIR}_{I_t, J_{t'}})) \). So it will be enough to lower-bound \( \text{Ent}(\text{DIR}_{I_t, J_{t'}}) \).

Fix any \( i \in I_t \). Our assignment \( y^* := 0^n \) satisfies

\[
 ||y^*[I_t; i]|| = 1.
\]

Thus for any \( x \), case 2 holds in the definition of DIR(x, y^*[I_t; i], r^*). Consider any \( j \in J \); substituting values into Eq. (2), we find

\[
 (\text{DIR}_N(x, y^*[I_t; i], r^*))_j = \text{shift}(x; i \cdot 2^{\ell-1})(j \mod 2^{\ell-1}) = x(j \mod 2^{\ell-1}) - 2^{\ell-1}.
\]

Thus, from the output of DIR_{I_t, J_{t'}}(x) we can determine \( x_a \), for each \( a \in J_{(\mod 2^{\ell-1}) - 2^{\ell-1} \cdot I_t} \). Here, \( J_{(\mod 2^{\ell-1})} := \{j' \in [0, 2^{\ell-1} - 1] : j' = j \mod 2^{\ell-1} \text{ for some } j \in J\} \).

We observe that actually \( J_{(\mod 2^{\ell-1})} = [0, 2^{\ell-1} - 1] \), since \( \hat{J} \)
is a consecutive interval of length $2^{l-1}$. Fact 3 now implies that
\[
\text{Ent}(\text{DIR}_{I_1, I_2}) \geq \left|\left[0, 2^{l-1} - 1\right] - 2^{l-1} \cdot I_1\right|.
\]
Recall that $I_1$ is an interval of length $\lceil n/p \rceil$. It follows that, with arithmetic taken over the integers $\mathbb{Z}$, the set $\left[0, 2^{l-1} - 1\right] - 2^{l-1} \cdot I_1$ is an interval in $\mathbb{Z}$ of size $2^{l-1} \cdot |n/p|$. We conclude that, over $\mathbb{Z}$,
\[
\left|\left[0, 2^{l-1} - 1\right] - 2^{l-1} \cdot I_1\right| = \min\{n, 2^{l-1} \cdot |n/p|\} \geq \min\{n, (p/4) \cdot |n/p|\} = \Omega(n).
\]
This proves Lemma 7.

C. Efficient bounded-depth circuits for DIR

In this subsection, we prove the upper bounds needed to establish Theorem 6.

First we prove the upper bound for depth 2, namely $s_2(\text{DIR}_N) = \mathcal{O}(N^{3/2})$. Our circuit construction will split into two cases, handled separately as follows: first, if $2^r < \sqrt{n}$, the needed substring of $x$ can be copied into $\sqrt{n}$ gates on Level 1 of the circuit, and then copied from this middle level by the output gates. On the other hand, if $2^r \geq \sqrt{n}$, then each output bit can depend on at most $\sqrt{n}$ possible bits of $x$.

**Lemma 8.** $s_2(\text{DIR}_N) = \mathcal{O}(N^{3/2}) = \mathcal{O}(N \cdot \lambda_1(N))$.

**Proof:** As before, we may assume $N = 2 \cdot 2^k + \lfloor \log_2 k \rfloor$, with $n := 2^k$. For convenience, we will assume further that $k$ is even, so that $\sqrt{n} = 2^{k/2}$ is an integer.

Recall that, when $||y|| = 1$, the output of $\text{DIR}_N(x, y, r)$ will consist of $2^{k-r}$ consecutive copies of a substring of length $2^r$. We will design two depth-2 circuits $C^\downarrow, C^\uparrow$, each with $\mathcal{O}(N^{3/2})$ wires. $C^\downarrow$ will compute $\text{DIR}_N$ under the promise that $2^r < \sqrt{n}$; $C^\uparrow$ will compute $\text{DIR}_N$ provided $2^r \geq \sqrt{n}$. It is then easy to combine these two circuits to get a single circuit computing $\text{DIR}_N$ under no assumption. (We apply each of $C^\downarrow, C^\uparrow$ to the input, merging their corresponding output gates.

Each output gate is also wired to the inputs of $r$, to determine whether it should output the value of $C^\downarrow$ or of $C^\uparrow$; this takes $\mathcal{O}(n \log_2 k)$ additional wires.)

For $C^\downarrow$, the basic idea is that when $2^r < \sqrt{n}$, fewer than $\sqrt{n}$ bits of $x$ actually “matter” for the output; we can extract these bits on Level 1 and distribute them to the appropriate outputs on Level 2. More precisely, we will have $\sqrt{n} + 1$ gates $(s, g_1, \ldots, g_{\sqrt{n}})$ on Level 1 of our circuit $C^\downarrow$, each wired to all of $(x, y, r)$. We set $s = 1$ iff $||y|| = 1$. The gates $g_1, \ldots, g_{\sqrt{n}}$ will simply copy the interval of size $2^{r} < \sqrt{n}$ in $x$ that must be replicated in the output of $\text{DIR}_N$, as determined by $x, r$, and $i = i(y)$. (This interval of bits from $x$ will be padded with $\sqrt{n} - 2^r$ zeros when copied to Level 1.)

Next, each output bit $z_t$ ($t \in \mathbb{Z}_n$) is wired to all Level 1 gates and to $r$. We won’t give an explicit rule, but it is clear that with these inputs, each $z_t$ can determine its correct output to compute $\text{DIR}_N$ (assuming here that $2^r < \sqrt{n}$). The number of wires in $C^\downarrow$ is $\mathcal{O}(n^{3/2} + n(\sqrt{n} + \log_2 k)) = \mathcal{O}(N^{3/2})$, as required.

Now we build $C^\uparrow$. The basic idea here is that, assuming $2^r \geq \sqrt{n} = 2^{k/2}, each output bit $z_t$ depends only on $y, r$, and on input bits $x_t$ for which $t - t'$ is a multiple of $\sqrt{n}$. Thus, after “compactifying” the relevant information in $y$ into $\sqrt{n}$ bits on Level 1, each output bit can be computed from the Level 1 gates, from $r$, and from $\sqrt{n}$ bits of $x$, using $\mathcal{O}(n^{3/2})$ wires in total. Details follow.

Let $H(y) = H(y) = (h_1, \ldots, h_{\sqrt{n}}) : \mathbb{F}_2^n \to \mathbb{F}_2^{\sqrt{n}}$ be the operator from item 1 of Lemma 1 that is injective on $\{e_1, \ldots, e_n\}$. We implement $H$ on Level 1 of our circuit with $\mathcal{O}(n)$ wires, following the construction in Lemma 1. As in $C^\downarrow$, on Level 1 we also include a single gate $s$, wired to $r$, that outputs 1 iff $||y|| = 1$. Thus the total number of wires between inputs and Level 1 is $\mathcal{O}(n)$, and there are $\sqrt{n} + 1$ gates at Level 1.

Next, each output bit $z_t$ ($t \in \mathbb{Z}_n$) is wired to all Level 1 gates, to all of $r$, and to the input bits $(x_{t+1}, x_{t+2}, \ldots, x_{t+(\sqrt{n}-1)})$. Thus our circuit is of depth 2, and the total number of wires to the outputs is $n \cdot (\sqrt{n} + 1 + \lfloor \log_2 k \rfloor + \sqrt{n}) = \mathcal{O}(n^{3/2})$.

Rather than specifying the output rule for $z_t$ precisely, we argue that this gate has all the information it needs to output $\text{DIR}_N(x, y, r)$, correctly (assuming $2^r \geq \sqrt{n}$). First, if $||y|| = 1$, then $z_t$ can learn this and output 0 by looking at $s$. Otherwise, $z_t$ knows that $||y|| = 1$. In this case, $z_t$ must output the bit shift $(x; i \cdot 2^r)_{(i \cdot (2^r \cdot 2^r) - 2^r})$ (here the outer index arithmetic is over $\mathbb{Z}_n$). This desired bit lies among $(x_{t+1}, x_{t+2}, \ldots, x_{t+(2^r \cdot 2^r) - 2^r})$, and these are contained in the inputs to $z_t$ since $2^r$ is a multiple of $\sqrt{n}$. Finally, the value $i = i(y)$ can be determined from $H(y)$, because $H(y)$ determines $y$ when $||y|| = 1$. Thus $z_t$ can output the correct value.

Next, we will develop tools for building more-efficient circuits of higher depths. For depth 3, we will show $s_3(\text{DIR}_N) = \mathcal{O}(N \log N)$. The plan for depth 3 is fairly simple: First, from an input $(x, y, r)$ satisfying $||y|| = 1$, we can extract the index $i = i(y)$ and the value $p := (i \cdot 2^r \mod n)$ in depth 1, with $n \log_2 n$ wires. Then we show that there is a circuit to compute the appropriate output given $(x, i, r, p)$ using $\mathcal{O}(N)$ wires in depth 2, under the promise that $r$ equals some fixed value $a \in [0, k - 1]$. As there are only $\log_2 n$ possible values of $r$, we can combine these circuits (merging their output gates) into a single circuit of total depth 3 and with $\mathcal{O}(N \log n)$ wires overall.

To build our circuits for depths 3 and higher, it is useful to introduce some auxiliary operators, which are “easier” versions of $\text{DIR}_N$. The first such operator further restricts the “admissible” values of $r$ to some interval $[a, b] \subseteq [0, k - 1]$. 
1. Define $\text{DIR}^{[a,b]}_N : \{0,1\}^{2n + \lceil \log_2 k \rceil}$ by

$$\text{DIR}^{[a,b]}_N(x, y, r) := \begin{cases} \text{DIR}_N(x, y, r) & \text{if } r \in [a, b], \\ 0^n & \text{otherwise.} \end{cases}$$

The second simplified operator makes the values $i$ and $p := (i \cdot 2^r \mod n)$ available in binary. Define $\text{DIR}^{\text{bin},[a,b]}_N : \{0,1\}^{n+k+\lceil \log_2 k \rceil+k}$ by

$$\text{DIR}^{\text{bin},[a,b]}_N(x, i, r, p) := \begin{cases} \text{DIR}^{[a,b]}_N(x, e_i, r) & \text{if } p = i \cdot 2^r \mod n, \\ 0^n & \text{otherwise.} \end{cases}$$

We are abusing notation slightly, since the input size to $\text{DIR}^{\text{bin},[a,b]}_N$ is actually smaller than $N = 2n + \lceil \log_2 k \rceil$.

The next useful lemma handles a fixed value $a$.

**Lemma 9.** For any $a \in [0,k-1]$, there is a depth-2 circuit $C^a$, using $O(n)$ wires, that computes $\text{DIR}^{[a,b]}_N$.

**Proof:** Let $a$ be fixed. We include a single gate $s$ on Level 1 that outputs 1 iff all of the following hold:

1. $||y|| = 1$;
2. $p = i \cdot 2^r \mod n$;
3. $r = a$.

Also on Level 1 of the circuit $C^a$, we define gates $x'_t$, for $t \in \{0,1,\ldots, 2^a - 1\}$. Each such gate is wired to the $(k - a)$ most significant bits of $p$, and to the inputs $(x_t, x_{t+1}, \ldots, x_{t+(2^a-a-1)2^a})$. Let $\tilde{p} := p - (p \mod 2^a)$ be the value obtained by assuming that the unseen bits of $p$ are zero. We then set $x'_t := x_t - \tilde{p}$.

Finally, given an output gate $z_j$ of $C^a$ with $j \in \mathbb{Z}_n$, we set $z_j := x'_j \wedge s$, so that the output gates have $2n$ incoming wires in total, and the entire circuit $C^a$ is depth-2 and contains $O(n)$ wires.

We claim that $C^a$ has the desired behavior. To see this, fix any $j \in \mathbb{Z}_n$. First, if $s = 0$ then $z_j = 0$ as needed. Next assume that $s = 1$, so that $\text{DIR}^{\text{bin},[a,b]}_N(x, i, r, p) = \text{DIR}_N(x, e_i, a)$. We compute

$$z_j = x'_j \mod 2^a \wedge 1 = x'_j \mod 2^a \wedge s = (\text{shift}(x'_i \cdot 2^a)) \mod 2^a,$$

as needed. This proves the correctness of $C^a$. ■

**Lemma 10.** For any $0 \leq b < k$, $s_2(\text{DIR}^{\text{bin},[0,b]}_N) = O(N \ln N)$. Also, $s_3(\text{DIR}_N) = O(N \ln N) = O(N \cdot \lambda_2(N))$.

**Proof:** Again assume that $N = 2 \cdot 2^k + \lceil \log_2 k \rceil$, with $n := 2^k$. First we show $s_2(\text{DIR}^{\text{bin},[0,k-1]}_N) = O(N \ln N)$. Let $(x, i, r, p)$ be the inputs. We apply the circuits $C^{0}, C^{1}, \ldots, C^{b}$ from Lemma 9 to $(x, i, r, p)$. Each such circuit $C^a$ has $n$ outputs, call them $z_{0,a}, \ldots, z_{n-1,a}$.

For $t \in \mathbb{Z}_n$, we “merge” $z_{t,0}, \ldots, z_{t,b}$ into the single output gate $z_t$ (which takes all the inputs of $z_{t,0}, \ldots, z_{t,b}$ as its inputs). This gate is also wired to the input $r$, and it outputs $z_t$.

Let $C$ denote the circuit we have constructed. That $C$ computes $\text{DIR}^{\text{bin},[0,b]}_N$ is immediate. $C$ is of depth 2 since each $C^a$ is of depth 2, and $C$ has $O(N) \cdot (b+1) + n \cdot \lceil \log_2 k \rceil = O(N \ln N)$ wires, since each $C^a$ has $O(N)$ wires and $b < k = \log_2 n$.

Next we show $s_3(\text{DIR}_N) = O(N \ln N)$. In our circuit $C'$ for $\text{DIR}_N$, we will assume that the input satisfies $||y|| = 1$. As usual, it is easy to modify this circuit to handle the case where $||y|| \neq 1$.

On Level 1 of our circuit, we compute $i = i \cdot 2^r \mod n$. This takes $O(n \ln n)$ wires since $i,p$ are $k$ bits each. Next, we set $b := k-1$ and apply our previously constructed circuit $C$ for $\text{DIR}^{\text{bin},[0,k-1]}_N$ to $(x, i, r, p)$. By definition, the resulting output is $\text{DIR}_N(x, y, r)$. Our construction of $C'$ is of depth $1+2 = 3$ and contains $O(N \ln N)$ wires.

To work with depths larger than 3, we will give a technique that allows us to “shrink” the size of an instance of the Dyadic Interval Replication problem, discarding most of the irrelevant bits of $x$, when the value $r$ is not too large.

The next lemma collects two variants of this process.

**Lemma 11.** Let $N = 2 \cdot 2^k + \lceil \log_2 k \rceil$. Let $0 \leq a \leq b \leq k-1$ be given, and let $d = d(N) \geq 1$. Let $N' := 2 \cdot 2^k - a + \lceil \log_2 (b-a+1) \rceil$.

1. There is a depth-$(d+2)$ circuit $C$ that computes $\text{DIR}^{\text{bin},[a,b]}_N$; the number of wires in $C$ is $2^{a+1} \cdot s_d(\text{DIR}^{\text{bin},[0,b-a]}_N) + O(N)$.

2. There is a depth-$(d+3)$ circuit $C'$ that computes $\text{DIR}^{\text{bin},[a,b]}_N$, and has $s_d(\text{DIR}^{\text{bin},[a,b]}_N) + O(N(k-b))$ wires.

In each case the $O(\cdot)$ is independent of $a,b,d$.

**Proof:** (1) We split into two cases according to weather the input $p$ satisfies $p = 0 \mod 2^{k+1}$, designing a different depth-$(d+2)$ circuit for each case. In each case we give a circuit with $2^a \cdot s_d(\text{DIR}^{\text{bin},[0,b-a]}_N) + O(N)$ wires. It is then easy to combine the two circuits using $O(N)$ additional wires. We assume in the following construction that $p \neq 0 \mod 2^{k+1}$, and then sketch the other (quite similar) case.

On Level 1 of $C$, we include gates $x' = (x'_0, \ldots, x'_{2^b+1-1})$, where $x'_0$ is wired to $(x_t, x_{t+2^b+1}, \ldots, x_{t+(2^b-a-1)2^a})$, and also to the $k-b-1$ most significant bits of $p$, that is, to $p_{b+1}, \ldots, p_{k-1}$. We set
\[x'_t := x_{t-\tilde{\beta} - 2^{b+1}}, \quad \text{where} \]
\[\tilde{\beta} := \sum_{t=0}^{k-1} p \cdot 2^t = p - (p \mod 2^{b+1}).\]

The next Lemma, our key algorithmic tool for depths \(d \geq 5\), we first obtain binary representations of the values \(i = i(y), p = i \cdot 2^r, \) in depth 2 and \(O(n)\) wires, using the mapping \(H\) from Lemma 1. (See the proof of Lemma 14 for details of this process. As usual, we can handle cases \(||y|| \neq 1\) separately.) Then we use the depth-2 circuits \(C^a\) from Lemma 9 to compute \(\text{DIR}^{[\ln n, [0, b - a]]}(x, i, r, p)\) for \(a = \{b + 1, \ldots, k - 1\}\), which gives the outputs of \(\text{DIR}^{[b+1, b+1]}, \ldots, \text{DIR}^{[k-1, k-1]}\) we need. Each \(C^a\) has \(O(n)\) wires, so the total cost of computing \(\text{DIR}^{[b+1, b+1]}, \ldots, \text{DIR}^{[k-1, k-1]}\) is \(O(n(k - b)) = O(n \ln n)\).

At Level 5 of our circuit, we combine the outputs of all of our subcircuits: we "merge" the gates giving the values \((\text{DIR}^{[0, b]}), (\text{DIR}^{[b+1, b+1]}), \ldots, (\text{DIR}^{[k-1, k-1]})\) into a single output gate \(z_j\) computing the OR of these values. By Eq. (3), this circuit computes \(DIR^N\); it is of depth 5 and contains \(O(n \ln n)\) wires. This proves the Lemma.

The next lemma, our key algorithmic tool for depths \(d > 5\), gives an inductive construction of ever-more-efficient circuits for \(\text{DIR}^{[0, b-1]}\) at the cost of increasing the circuit depth.

\textbf{Lemma 13.} For every values \(d = d(N) \geq 2\), we have \(s_d(\text{DIR}^{[0, b-1]}) = O(N \cdot \lambda_d(N))\). The \(O(\cdot)\) is independent of \(d\).

\textbf{Proof:} Let \(C > 0\) be chosen larger than the implicit constants in the \(O(\cdot)\)-notation used in all of our previous results, when the bounds are, for convenience, re-expressed in terms of the parameter \(n = (\Theta(N)); in each case the bound
was independent of \(d\). We claim, and prove by induction on even \(d \geq 2\), that \(s_d(DIR_N^{bin,[0,k-1]}) < 40CN \cdot \lambda_d(n)\). We may assume in what follows that \(k > 20\), setting \(C\) large enough that the claim is trivially true for \(k \leq 20\).

For \(d = 2\), Lemma 10 gives \(s_2(DIR_N^{bin,[0,k-1]}) < CN \cdot \lambda_2(n)\), as needed. Now let \(d \geq 4\) be even, and consider the statement proved for \(d' = d - 2\). First, if \(\lambda_{d-2}(n) = 1\), the result is trivial; so assume from now on that \(\lambda_{d-2}(n) \geq 2\). Define a nondecreasing integer sequence \(a_1, a_2, \ldots, a_T\), where

\[a_t := \left\lceil \log_2(n/\lambda^{(t)}_{d-2}(n)) \right\rceil - 20\]

(recalling that \(g^{(t)}\) denotes the \(t\)-fold composition of \(g\)). We let \(T := \min\{t : \lambda^{(t)}_{d-2}(n) = 1\}\); thus \(T = \lambda^{(d-2)}_{d-2}(n) = \lambda_d(n)\) by the definitions. It is immediate that \(\lambda^{(d-2)}_{d-2}(m) \geq 1\) whenever \(m > 1\), so in fact \(\lambda^{(d-2)}_{d-2}(n) = 1\) and all the \(a_t\)s are well-defined, with \(a_T = 20\). Also, \(T > 1\) by our assumption \(\lambda_{d-2}(n) \geq 2\).

Let \(\lambda^{*} := \min\{t \in \{T\} : a_t > 0\}\). As \(a_T = 20\), we can express the interval \([0, k-1]\) as \([0, k-1] = [0, a_1] \cup [a_1, a_2-1] \cup \cdots \cup [a_T, k-1]\), and for \(j \in \mathbb{Z}_n\) we can write

\[
(DIR_N^{bin,[0,k-1]})(j) = (DIR_N^{bin,[0,a_1]})(j) \lor
\]

\[
(DIR_N^{bin,[k-19,k-1]})(j) \lor \bigvee_{t=t^{*}+1}^{T} (DIR_N^{bin,[a_{t-1},a_{t}]})(j).
\]

By the same technique used in Lemma 12, one can combine depth-\(d\) circuits for \(DIR_N^{bin,[0,a_1]}\), \(DIR_N^{bin,[a_1,a_2]}\), \(\ldots, DIR_N^{bin,[a_{T-1},a_T]}\), and \(DIR_N^{bin,[k-19,k-1]}\) to get a depth-\(d\) circuit for \(DIR_N^{bin,[0,k-1]}\).

Let \(\tilde{N} := 2 \cdot 2^{a_T+1} + \left\lceil \log_2(a_T + 1) \right\rceil\). Applying Lemma 11, part 1, we find that

\[
s_{d}(DIR_N^{bin,[0,a_1]}) \leq s_{d-2}(DIR_N^{bin,[0,a_1-1]}) + Cn.
\]

If \(t^{*} = 1\), then \(2^{a_T+1} \leq 2^{-19} \cdot (n/\lambda_{d-2}(n))\), and, using the inductive hypothesis,

\[
s_{d-2}(DIR_N^{bin,[0,a_1-1]}) \leq 0.1C \cdot (n/\lambda_{d-2}(n)) \cdot \lambda_{d-2}(n),
\]

so that \(s_{d}(DIR_N^{bin,[0,a_1]}) < 1.01Cn\). If \(t^{*} > 1\), then \(2^{a_T+1} \leq 2^{a_T-1} \cdot \lambda_{d-2}(n)\), and

\[
s_{d-2}(DIR_N^{bin,[0,a_1-1]}) \leq 40C \cdot 2^{a_T-1} \cdot \lambda_{d-2}(n),
\]

so \(2 \lambda_{d-2}(\lambda_{d-2}(n)) \leq 160C^2 \lambda_{d-2}(n) < Cn\) (here using \(k > 20\)), so that \(s_{d}(DIR_N^{bin,[0,a_1]}) \leq 2Cn\) in this case.

Now consider \(t \in \{t^{*} + 1, T\}\). By Lemma 11, part 1, we have

\[
s_{d}(DIR_N^{bin,[a_{t-1},a_{t}]}) \leq 2^{a_T+1} \cdot N_t \cdot (4 \lambda_{d-2}(n)) + Cn,
\]

where \(N_t := 2 \cdot 2^{a_T-1} + \left\lceil \log_2(a_T - 1 + 1) \right\rceil\). Now \(2^{a_T-1} \leq 4 \cdot \lambda_{d-2}(n)\), so using the inductive hypothesis, \(s_{d-2}(DIR_N^{bin,[0,a_{T-1}]}))\) is at most \(40C \cdot 4^{n/\lambda_{d-2}(n)}\).

\[\lambda^{(t-1)}_{d-2}(n)/\lambda^{(t)}_{d-2}(n)) \cdot \lambda^{(t-1)}_{d-2}(n)) = 640C\lambda^{(t-2)}_{d-2}(n))\].

Thus, \(s_{d}(DIR_N^{bin,[a_{T-1},a_{T}]})\) is at most

\[
g^{a_T-1} \cdot (640\lambda^{(t-1)}_{d-2}(n)) + Cn < 0.1Cn,
\]

using the definition of \(a_t\).

Finally, \(DIR_N^{bin,[k-19,k-1]}\) can be computed with \(19Cn\) wires, using 19 applications of Lemma 9. Combining our cases and applying them to Eq. (4), we find that \(s_{d}(DIR_N^{bin,[0,k-1]}))\) is less than \(19Cn + 2Cn + T \cdot (1.01Cn) < 40Cn \cdot \lambda_d(n)\), since \(T = \lambda_d(n)\). This extends the induction to \(d\), completing the proof.

\[\square\]

**Lemma 14.** For even \(d \geq 6\), we have \(s_{d}(DIR_N) = O(N \cdot \lambda_{d-2}(N))\); the \(O(\cdot)\) is independent of \(d\).

**Proof:** As usual, we may assume the input satisfies \(||y|| = 1\) (handling the case \(||y|| \neq 1\) separately with \(O(N)\) additional wires).

On Level 1 of our circuit \(C\) for \(DIR_N(x,y,r)\), we compute \(H(y)\), where \(H\) is the mapping defined within Lemma 1; \(H\) is injective on \(\{e_1, \ldots, e_n\}\) and computable in \(2n\) wires. On Level 2, we use \((H(y), r)\) to compute \(i = i(y)\) and \(p := i \cdot 2^T \mod n\); this takes \(O(\sqrt{n} \ln n) = o(n)\) wires. Finally, we apply an optimal depth-\((d-2)\) circuit for \(DIR_N^{bin,[0,k-1]}\) to the input \((x, i, r, p)\). This yields the desired output. The number of wires in our circuit is \(s_{d-2}(DIR_N^{bin,[0,k-1]})) + O(N)\), and by Lemma 13 this is \(O(N \cdot \lambda_{d-2}(N))\).

By collecting the upper bounds for \(DIR_N\) in Lemmas 8, 10, 12 and 14, along with the lower bounds we get from Theorem 5 and Lemma 7, we have proved Theorem 6.

**Acknowledgment**

I am grateful to Stasys Jukna for many helpful comments.

**References**


